
pycalibration Documentation

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This is the documentation of **pyCalibration**.

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1.1 pycalibration

python calibration support

Python library to supply basic common knowledge functionalities to support calibration

1.2 License

The MIT License (MIT)

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1.3 Contributors

- Jerome Douay <jerome@far-out.biz>

1.4 Changelog

1.4.1 Version 1.1.0

- MDF 3.0 time stamp correction
- small code error correction

1.4.2 Version 1.0.0

- large modification to code
- almost all classes with test procedure
- removes dcm as the code is broken, will be inserted again later on.

1.4.3 Version 0.8.0

- updates the vehicle class and correct some of the code errors
- introduces the watchdog. This allow to have a monitoring system of a directory and detect new files
- extract introduces the interpolation of points from measurement files to correct the different time frame problems
- Extract no longer accept add mutiple channels to avoid issue with size and interpolation. Only single channel add.

1.4.4 Version 0.7.0

Inserted multiple new objects

- DCM
- Value
- Map
- Vehicle
- Gearbox
- Engine

See the documentation on features inserted to this release

1.4.5 Version 0.6.2

Function

- process class show a progress bar to indicate processing progress

Extract

- Extract inherit MDF class. MDF should no longer be used directly, always use Extract to get data
- removed add multiple chanel as the code was unstable
- add_channel now support a paraemter to interpolate or not the value (not recommended for digital signals)

MDF

- Still in the package and documentation.
- Allow interpolation of channels

1.4.6 Version 0.6.1

- corrects error in MDF get data, allowing multiple signals for one rename. The first defined signal is used, order matter !

1.4.7 Version 0.6.0

MDF

- data returned contain the measurement time in the time column. Index is set to a datetime using the measurement time and the timestamp from the file

Function

- introduction of the function class
- base class for the development of functions in other packages
- process and lab method available

1.4.8 Version 0.5.0

Shift class inserted in the library. Documentation and test procedure available

1.4.9 Version 0.4.0

- Trigger class
- Trigger Documentation
- Trigger Test

1.4.10 Version 0.4.0

- MDF - Removed the set_rename and set_renames from the MDF to Extract - Documentation improved
- Extract - class introduced in this release - allow single file and multiple files - add signal (single and multiple)
- set rename (single and multiple) - get data
- Documentation - documentation update and made easier to read

1.4.11 Version 0.3.0

- MDF - Add_signals to add singlas from a list - set_rename to allow renaming a channel after it has been inserted - set_renames allow to rename multiple channel using a list - disabled get_all as MDFReader can only process by channel group, work around to be done later on
- Documentation - documentation generation code completed - using the read the doc template - basic documentation, need more work
- Tests - MDF test procedure checking for most of the features. - 78% tested, need to improve to get 100 %

1.4.12 Version 0.1

- Initial commit, throw a lot a few code from my head into files.

1.5 pycalibration

1.5.1 pycalibration package

Submodules

pycalibration.curve module

class pycalibration.curve.**Curve**(*x*, *y*)

Bases: `object`

Curve allow the defintion and extroplation of data of a curve

This class is usually returned by the DCM class after importing a file.

insert(*x*, *y*)

Insert a point in the curve

Parameters

- **x** – x value of the point
- **y** – y value of the point

Returns

None

y(*x*)

return the y value of a curve given the x value.

Values are interpolated between the points given

pocalibration.engine module

class pocalibration.engine.**Engine**(*n*=[600, 1000, 2000, 4000, 6000], *t*=[100, 500, 1000, 800, 100])

Bases: `object`

Class engine offers support for engine calculation and estimation.

npower(*power*)

power(*speed*, *limit*=100)

Return the Power at a given engine speed and a percentage torque :param speed: engine speed in rpm
:param limit: max percentage torque :return: engine power in watts

torque(*speed*, *limit*=100)

Return the torque at an engine speed with a max percentage torque (100% is full torque) :param speed:
engine speed in rpm :param limit: maximum percent torque from curve :return: engine torque in Nm

pocalibration.extract module

class pocalibration.extract.**Extract**

Bases: `MDF`

Extract class extract channels from single or multiple files

add_directory(*pathname*)

Add a directory recursively to the files to be processed. Files recognize are mdf and mf4 extensions

Parameters

path – path to be added

Returns

none

add_file(*filename*, *duplicates*=*True*)

Add single file to the list of files to be processed

Parameters

- **file** – file name path to the file
- **duplicates** – allow duplicates in the list of files

Returns

none

get()

Read the MDF files and retrieved the requested data.

Returns

list of pandas dataframe containing the datas.

pycalibration.function module

class pycalibration.function.**Function**

Bases: `Extract`

Base class to define function in module

Based on `Extract`, it supports all the `extract` method. It is necessary to set the files or directory to process before calling the `process` method.

Evaluate method should be overwritten for data evaluation related to the function being developed.

evaluate(*data*)

Using the data retrieved from the measurement file, generate calibration. This method should be overwritten by the derivative class and returns whatever the evaluation is producing.

Returns

should return the evaluation data

lab()

Write the labels and parameters in a lab file

Returns

`None`

process()

Retrieve the necessary information from the measurement files.

Returns

list containing files processed results

pycalibration.gearbox module

class pycalibration.gearbox.**Gearbox**(*n*=[1, 2, 3, 4, 5], *r*=[10, 9, 8, 7, 6])

Bases: `object`

Gearbox class. Class provides interface to get the gear ratio on a given gear

ratio(*gear*)

Return the gear ratio for a given gear :param gear: gear number :return: gear ratio

pycalibration.map module

class pycalibration.map.**Map**(*x*, *y*, *z*)

Bases: `object`

x(*y*, *z*)

y(*x*, *z*)

z(*x*, *y*)

pocalibration.mdf module

class pocalibration.mdf.**MDF**(filename=None)

Bases: `object`

MDF class to handle MDF read operation

add_channel(channel, rename="", inter=False)

Set a channel to be retrieved from the MDF. If a rename name is supplied, the channels will be renamed. If more than one channel as the same rename name, all channels will be checked until one available is found. Interpolation should not be used on digital signal. The interpolation is linear and should be used on non digital signals to improve accuracy. If signal in measurement with multiple time raster.

Parameters

- **channel** – channel name
- **rename** – name to be renamed to
- **inter** – Set to True to interpolate missing values, default False.

Returns

None

get_channel(channel)

Get the data designated by the channel name

Parameters

channel – channel name

Returns

pandas dataframe containing the data

get_data()

Read the MDF file and retrieved the requested data

Parameters

filename – filename (with full path) of the MDF file to open

Returns

pandas dataframe containing the data. The time offset for the channels is set to the column offset. The dataframe index is based on the file timestamp with the measurement time offset. This allows datetime operation on the dataframe.

set_file(filename)

pocalibration.resistance module

class pocalibration.resistance.**Resistance**(cx=0, fr=0, ro=0)

Bases: `object`

This class calculates the vehicle driving resistance

fair(v)

Return the air resisting force :param v: vehicle speed in m/s :return: air resisting force in N

fpitch(m, grade)

Return the pitch resisting force at a specified pitch :param m: total vehicle mass in kg :param pitch: slope in percentage :return: pitch resisting force in N

frolling(*m, grade*)

Return the rolling resisting force :param m: total vehicle mass in kg :param pitch: slope in percentage
:return: rolling resisting force in N

resistance(*v, m, grade=0*)

Return the sum of air, pitch and rolling resisting force :param v: vehicle speed in m/s :param m: total vehicle mass in kg :param grade: slope in percentage :return: total resisting force in N

pocalibration.shift module

class pocalibration.shift.**Shift**

Bases: `object`

Generate Table before and after shifting All the columns supplied in the data for process will be used. At the beginning of the shift, the columns will be added ‘_pre’, at the end of the shift ‘_post’.

process(*data*)

Process the data and return the table containing the shifts.

Parameters

data – pandas Dataframe containing the data, inclusive the channel to be used to detect the shift

Returns

Pandas dataframe containing the pre and post shifts data.

set_post(*post, up=False*)

Set the post channel used for trigger

Parameters

- **pre** – Channel name to be used as trigger
- **up** – Determine the signal direction (up/down, up by default)

set_pre(*pre, up=True*)

Set the pre channel used for trigger

Parameters

- **pre** – Channel name to be used as trigger
- **up** – Determine the signal direction (up/down, up by default)

pocalibration.trigger module

class pocalibration.trigger.**Trigger**

Bases: `object`

Generate Table at the time of the event. The event shall be generated from a digital signal

process(*data*)

Process the data and returns the events in a pandas dataframe

Parameters

data – data to be analysed

Returns

pandas dataframe with all the signals and events

set_trigger(*name*, *up=True*)

Set the name of the trigger signal

Parameters

- **name** – name of the signal to be used as trigger (digital)
- **up** – True if the event is rising

Returns

None

pycalibration.value module

class pycalibration.value.**Value**(*x*, *y=None*, *z=None*)

Bases: `object`

Value class represent the informations stored in a parameter. Each value can be a single value, a curve or a map. All points are interpolated

x(*pos*)

Return the X value at a position (interpolated from the array) :param pos: position in the array :return: X value

y(*x*)

Return the Y value at a X position (interpolated from the array) :param pos: position in the array :return: Y value

z(*x*, *y*)

Return the Z value at a X,Y position (interpolated from the array) :param pos: position in the array :return: Z value

pycalibration.vbo module

class pycalibration.vbo.**VBO**

Bases: `object`

read(*filename*)

pycalibration.vehicle module

class pycalibration.vehicle.**Vehicle**

Bases: `object`

class to represent a vehicle and basic calculation for the vehicle configuration

energy(*n*, *gear*, *mass*)

engine_to_speed(*engine*, *gear*)

Returns the vehicle speed from the engine speed and the common powertrain ratio :param engine: engine speed in 1/min :param gear: gear number :return: vehicle speed in m/s

force_to_torque(*f*, *gear*)

Returns the engine torque from the traction force and the common powertrain ratio :param f: traction force in N :param ratio: common powertrain ratio :return: engine torque in Nm

fresist(*speed, mass, grade=0*)

Returns the resistance force by entering the vehicle speed and the ratio (default ratio = 1) :param speed: vehicle speed in m/s :param mass: total vehicle mass in kg :param grade: road grade :return: resistance force in N

ratio(*gear*)

return the gear ration from the given gear

Parameters

gear – gear number

Returns

trans ratio (gear and rear axle ratio)

speed_to_engine(*speed, gear*)

Returns the engine speed from the vehicle speed and the common powertrain ratio :param speed: vehicle speed in m/s :param gear: gear number :return: engine speed in 1/min

torque(*n, pedal=100*)

By default, this function returns the torque at an engine speed with a max percentage torque (100% is full torque) :param n: engine speed in rpm :param pedal: percentage value of the accelerator pedal; default 100% means full torque :return: engine torque in Nm

torque_to_force(*t, gear*)

Returns the traction force from the engine torque and the common powertrain ratio :param t: engine torque in Nm :param ratio: common powertrain ratio :return: traction force in N

pocalibration.watchdog module

class pocalibration.watchdog.**Watchdog**(*queue, path=.'*)

Bases: FileSystemEventHandler

on_created(*event*)

Called when a file or directory is created.

Parameters

event (DirCreatedEvent or FileCreatedEvent) – Event representing file/directory creation.

on_moved(*event*)

Called when a file or a directory is moved or renamed.

Parameters

event (DirMovedEvent or FileMovedEvent) – Event representing file/directory movement.

process(*path*)

start()

stop()

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